

ZERO ROBOTICS

ISS PROGRAMING CHALLENGE

Middle School Summer Program
Session 1 Tag up
June 5, 2015



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- Complete and provide info to state coordinator (excel doc.)
- Student accounts (creating student accounts)
- Team Management (add students to the ZR team roster)
- ZR Evaluation (educator, student, training/pre-post)
- Review Schedule of program
- Review location of materials
- Update on new materials
 - Game CoronaSPHERE_MS_2D
- Questions
 - getmyZRState example



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Questions?



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What do I do if my student does not have an email account, and does not have parental permission to create an email account?

1. Email zerorobotics@mit.edu with the first name and last name of the student
2. The ZR team will set up that student with a “sandbox” account and reply to you with the following details:
 - username: firstname@zerorobotics.mit.edu
 - password: zerorobotics

Email	Is lead?
FirstName@zerorobotics.mit.edu	<input type="checkbox"/> Is lead? Remove

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Invite Students to Your Team



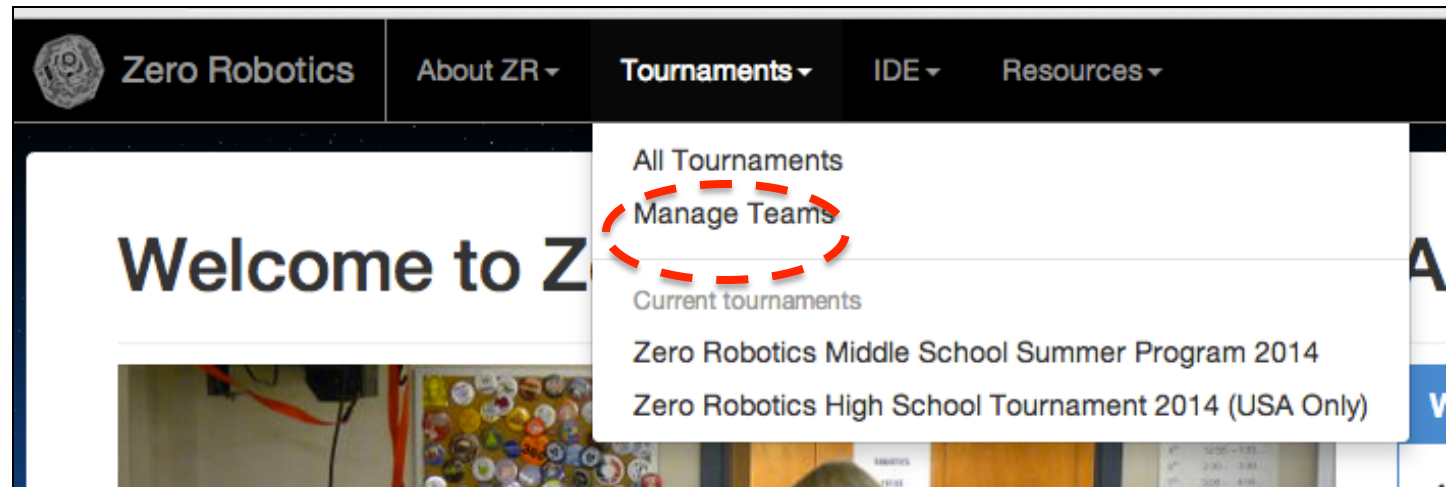
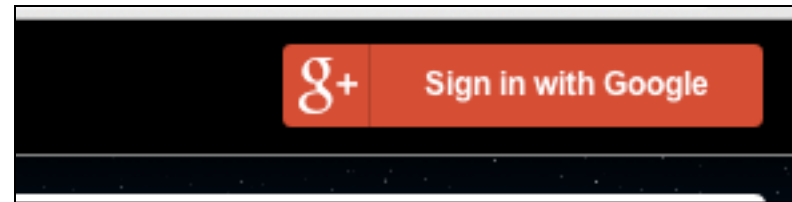
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To begin:

- Log into the ZR website
- From the “Tournaments” menu select “Manage Teams”



Invite Team Members (cont.)



If you are a team lead a window will open with:

- Team information
- Team Roster

Edit the information as desired

SPECIAL #1 Sample Team
Save

Team name

School

City

State (US Only)

Country

Team Website

Team Roster

New member's email Add

Email	Is lead?	
FirstName@zerorobotics.mit.edu	<input type="checkbox"/> Is lead?	Remove
John_doe@zerorobotics.mit.edu	<input checked="" type="checkbox"/> Is lead?	Remove

Not a team lead?
A window will open with the Team Name only like this:

Zero Robotics
About ZR ▾
Tournaments ▾
IDE ▾
Reso

SPECIAL #0 ZR Staff
Remove me from this team



Only Team Leads can add new Team Members

To add team members:

- Type in the team member's email used on the ZR site and click "Add"
- The team member will appear in the roster below.
- Uncheck the "is lead?" box for members that are not team leads.

Team Roster

New member's email Add

Email	Is lead?	
FirstName@zerorobotics.mit.edu	<input type="checkbox"/> Is lead?	Remove
John_doe@zerorobotics.mit.edu	<input checked="" type="checkbox"/> Is lead?	Remove

Reminder: Each user added as a Team Member must have already created a ZR account



- ***Educator***

- ***PRE-surveys must be complete before start of program***
- If you did not participate in a group training and have not completed an educator pre-survey, you must complete this survey asap: <http://zrindedpre.questionpro.com>
- ***POST-survey must be completed on the last day of program – link will be sent in wk 4***

- ***Student***

- ***PRE-surveys must be complete on first day of program***
- All Students must complete this survey on the first day of the program: <http://zrmidstudentpre.questionpro.com>
- ***POST-survey must be completed on the last day of program – link will be sent in wk 4***



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Schedule	Competition Elements	Curriculum Units
Week 1	Introduction	To Infinity and Beyond!
Week 2	Field Day	Developing a Strategy
Week 3	Intramurals/Practice Regional Competition	Time to Play!
Week 4	Regional Competition	Going the Distance
Week 5	ISS Collaboration	Reach for the Stars
Mid- Aug	ISS Finals!	

Note: Due to ISS availability, the ISS Finals date is not fixed until ~3 weeks before event.



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Schedule 1 Code Submittal dates



Week	Day	Time	Submit Code for:
1			
2			
3	Friday, June 26	5 PM	Practice Regional Competition
4	Friday, July 3	5 PM	Regional Competition
5	Thursday, July 9	5 PM	ISS Competition
ISS Finals Event			



- zerorobotics@mit.edu
- ZR Forum
 - (ZR website → Resources → Forum)
- MIT undergraduate researchers
- Your SAN Lead



- Show Intro video
- Review location of materials
- Update on new materials
 - Game CoronaSPHERE_MS_2D

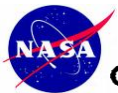


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getMyZRState



“getMyZRState” retrieves ZR state information (position, velocity, pointing vector, rates) for current satellite

	My_ZR_State			
Position	X: 0.0	Y: 0.0	Z: 0.0	[0] [1] [2]
Velocity	Vx: 0.0	Vy: 0.0	Vz: 0.0	[3] [4] [5]
Pointing vector	Nx: 0.0	Ny: 0.0	Nz: 0.0	[6] [7] [8]
Rotation rates	ω_x : 0.0	ω_y : 0.0	ω_z : 0.0	[9] [10] [11]



myZRstate[0] = x-coordinate

myZRstate[1] = y-coordinate

myZRstate[2] = z-coordinate



```
loop
  get My ZRState myZRstate
  if step == 0
  then GoToPositionA
  else if step == 1
  then GoToPositionC
  else step = 0
```